**Generative Affective Intelligence: A Topological Approach with Lie Manifolds**

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**Flow:**

1. **Despite being visually apparent that emotions come from physiology, there exist conflicting interpretations from unstandardized modeling approaches. The current successful ML methods (transformers) are not transferable to emotion modeling and datasets are not well formed, preventing any standardized and big-data approaches.**
2. **From a psychological perspective (foundational theory), anxiety is a compilation of emotions that start as physiological perturbations. These reflexes are not learned and exist across species, cultures, and life experiences. This can easily be visually decoded. From a machine learning perspective, emotion modeling is difficult due to small multimodal input-output spaces with little to no overlap across datasets. Meta-learning can fix the issue of multi-modal input-output spaces and neural operators can help with generalize from a discrete to continuous domain. We should employ these techniques in a new foundational architecture that can handle differently sampled data similar to transformers, without losing the temporal information.**
3. **We propose Observational Learning as a new foundational architecture to overcome these challenges. OL architectures train an inverted model: generating an output causal signal that explains all observable inputs. The hypersampled profile can now accommodate different input sampling frequencies and missing data as it hallucinates each biomarker signal independently and only backpropagates on the observed timepoints. By decoupling each biomarker, OL models aims to justify each discretely sampled observable biological reaction, without needing the continuous signal, allowing it to adapt to different sampling frequencies.**
4. **Introduction to the datasets and therapy.**
5. **Summation**

**Abstract.**

**Summary paragraph.**

~~Advances in wearable technology have enabled the collection of various anxiety-based physiological datasets across multiple sensors and emotional questions; however, reliably associating these signals with emotional states remains an unsolved problem. This study presents a new neural architecture called Observational Learning for merging physiological datasets that enable researchers to work on fragmented out-of-domain datasets that currently cannot be meta-trained together. This work demonstrates the potential to share wearable data across platforms not only within mental health, but also other continuous health monitoring systems, enhancing the capabilities of wearable healthcare and offering insights into designing more robust, adaptive systems that respond to complex physiological patterns in real time.~~

**Main.**

While physiological responses have been foundational for emotional expression, deriving generalized affective intelligence across wearables remains challenging when such physiological signals are temporally fragmented across inconsistent biomarkers, emotional labels, and temporal resolutions, hindering personalized mental health interventions. Yet, while tracking affective biomarkers1, Darwin visually identified universal reflexes across the animal kingdom that are strongly linked to emotional sensations, suggesting that some affective and biological states are simple enough to be observably coupled2. Current large language models (LLMs) can reliably extract highly encoded affective information across multi-lingual text-snippets, but depend on transformer architectures designed for semantic correlations, not temporal patterns, diminishing their success within physiological domains3. Attaining wearable artificial affective intelligence (AAI) for personalized human-computer interactions will require a universal affective computing interface that can provide quantitative comparison metrics across future research into personalized health datasets4, similar to the generalizability of current sentiment text-analysis frameworks5.

As early as Freud, psychophysiological models have studied momentary state anxiety (s-anxiety) through a compilation of emotions6 that originate within physiological perturbations7. While Spielberger quantified these affective expressions in the ***State-Trait Anxiety Inventory*** (STAI), a rigorously validated questionnaire (α=0.86−0.96) that has been independently verified across cultures, age groups, professions, ethnicities, genders, and languages11–15, there are no reproducible physiological-based models whose STAI scores can be extended across different biomarkers or affective labels4. This contrasts practical, quantitative methods in health and wellness models that average out subjective experimental variability across populations and over time to derive actionable wellness insights17. In machine learning, this concept is reflected in meta-learning, where a model learns a core set of adaptable transformations to address varying formulations of a problem, effectively learning the problem space rather than a single task18. To generalize a time-series signal, neural operators—mathematical constructs that map discrete observations to continuous functional domains—are foundational for physics-informed neural networks that solve differential equations19. Meta-learning neural operators therefore provide medical machine learning models with a continuous interpretable latent space that is critical before medical intervention.

We chose to abstract the problem of time-series signal embedding across the subspace of physiological signals collected from and validated across seven research-grade platforms, two of which were internally collected with a proposed Emotion Monitoring PAtch for TherapeutiC Healthcare (EMPATCH) that serves as an affective computing interface to experimentally validate our model.

As early as Freud, psychophysiological models have examined momentary state anxiety (s-anxiety) as a compilation of emotions originating from physiological perturbations.⁶ While Spielberger quantified these affective expressions through the State-Trait Anxiety Inventory (STAI)—a rigorously validated questionnaire (α=0.86−0.96) independently verified across cultures, age groups, professions, ethnicities, genders, and languages¹¹–¹⁵—no reproducible physiological-based models exist that can extend STAI scores across varying biomarkers or affective labels. This stands in contrast to practical, quantitative methods in health and wellness modeling, which average out subjective experimental variability across populations and over time to derive actionable wellness insights. This solution is known as meta-learning, from a computational perspective, where  a model learns a core set of adaptable transformations with context from different data groups. Meta-learning effectively captures the problem space, simplifying the solution-space.

the problem within a simpler manifold abstraction of ab indispensable when generalizing time-series signals, where neural operators—mathematical constructs that map discrete observations to continuous functional domains—serve as foundational tools. These neural operators underpin physics-informed neural networks designed to solve differential equations and model complex dynamics. By extension, meta-learning neural operators empower medical machine learning models to establish a continuous, interpretable latent space that bridges fragmented physiological data with affective labels, enabling precision interventions and expanding the scope of affective computing into actionable, real-world applications.

In this study, we introduce *Observational Learning* (OL) as a new generative meta-learning framework for projecting different physiological subspaces (EEG headbands, Empatica watches, respirators) onto a common manifold, thereby encoding a set of ‘n’ affective responses within a shared 2-dimensional time-series profile. Traditionally, manifolding learning often removes information through a change of basis, involving autoencoders, principal component analysis (PCA), or local linear embeddings (LLE). From an entropy perspective, all compressions are lossy, where the missing information can be recovered from the eigenvectors or model weights; however, these eigenvectors transformations are arbitrary and are not unique. Instead of searching for one of many shared basis vectors, we chose a simple interpretable basis along 2-dimensional rotations. Formally, instead of learning N 1-dimensional principal components, we learn N\*(N-1)/2 givens angles for fixed rotational axes that represents any arbitrary SO(n) transformation. Each weight is therefore a rotation that can be easily visualized within the Lie algebra plane. Furthermore, the model ensures stability where vanishing weights are equivalent to an identity rotation.

**Methods.**

**Lie Manifold Architecture.** Feed forward neural layers maximize a model’s expressive output through the form , where is any differentiable, non-linear function, is a square matrix with dimensions, and are input features and output labels respectively. This functional map is justified by the *universal approximation theorem*, which asserts that any continuous function can be approximated as one complementary pair of linear and non-linear transformations. We propose a simple, but consequential modification to this formula by taking the matrix exponential of a learnable skewed symmetric matrix, .

Where is a learnable normalization factor between [0.9, 1.1].

Importantly, the matrix exponential of a skewed symmetric matrix forms a special orthogonal group transformation SO(n), which is a Lie group representing distinct 2D rotations in N-dimensional space. T

which are related to the eigenvalues , where are the eigenvalues of , through the following relationship.

with computational complexity for learnable parameters

1. is always diagonalizable and is diagonalizable in 2D Jordan blocks.
2. form both a Lie group and Lie manifold, representing an -dimensional rotation.
3. If A has even dimensions, then all eigenvalues of are imaginary.
4. The eigenvalues where are the eigenvalues of .
5. The transformation is always invertible with .
6. The Hermitian adjoint of is .
7. is an orthogonal matrix with .
8. learnable degrees of freedom .

Unfortunately, real-world human-computer interfaces generally have arbitrary gaps spread over complex biometric feature signals, distorting prediction instances with consequential health impacts. We propose instead learning

Lie manifold learning instead applies the linear transformation

the transformation operator

a Lie manifold through the matrix exponential with the form.

symmetry

We propose to first project the signals

Compare error

Observational

Constructing the invertible layers

Lipschitz / Lie Group

Training the inverse direction

Inference

Data collection via WiFi and minimal lost packets

This study applies observational methods to explain affective

perturbations from a normal state that can be perturbed, such as bremsstrahlung radiationwithin medical imaging, protein-protein interactions, or transition states withion chemical mechanisms. We maintain a lossless invertible network by exponentiating skewed symmetric matrices, which have purely imaginary eigenvalues that represent the sin of 2D givens rotation angles. We allow a layer’s Lipschitz constant to vary by projecting each rotation operator into a non-linear subdomain.

from different biomarker signals, observational models time-reverse the problem by learning invertible transformations to *explain* how a generated signal, termed the health profile (hP), can account for all on-body biometric features. This approach bounds the searchable embedding space by starting at the hP manifold before linking back to each biometric response; meanwhile, inverting the network easily recovers the forward solution. We avoid costly inv

This approach mirrors the scientific method in solving inverse problems by learning a Green’s functional transformation that maps how observable features are distorted within a dynamic biological system.

Each invertible layer applies a rotation (orthonormal linear matrix)

nlike ‘black box’ machine learning approaches,

Therefore, observational learning provides a framework to decouple each input–output layer to accommodate any number of correlated emotion labels and vital signs across questionnaires and sensor modalities—within a compression limit—without needing to remove information via feature-selection beforehand.

The input layer’s flexibility allows the model to accommodate any number of correlated emotion labels and vital signs present across questionnaires and sensor modalities, within a compression limit, without the need to remove information from feature-selection beforehand.

Unlike ‘black-box’ machine learning approaches where the output is tuned to the input, observational learning provides a framework to decouple each input-output layer to

Our model was validated across four out-of-domain datasets within the literature as well as exhibits few-shot learning capabilities for predicting new complex emotions arising from different biological domains.

The objective function co-learns a lossless embedding of all biometric information using a shared metamodel with only 2.6% of weights being signal-specific.

using signal-specific linking layers to connect any arbitrary biological sensor to the main model.

visualization of the covariant shift across deep networks, allowing for layer-level training resolution.

In this study, we introduce the first real-time Emotion Monitoring PAtch for TherapeutiC Healthcare (EMPATCH) by integrating observational learning within electronic skin (e-skin), enabling actionable in-home mental health interventions based on clinical STAI-Y2 emotions. Previous work has shown that the softness, thinness, and gas permeability of skin-interfaced electronics are crucial for long-term, high-fidelity monitoring of physiological states. Recent developments in ultrathin, soft wearable devices—such as elastomeric nanofiber mats, elastic conductors with microcracked structures, and semiconductors—have enabled seamless skin contact. However, these devices often rely on time-consuming fabrication methods (e.g., electrospinning, iterative spin coating, and thermal evaporation), which are restricted by the size and capabilities of standard equipment like spin coaters and oxygen plasma cleaners. Such constraints make it challenging to produce large-area patches suitable for head or facial applications. Although float assembly methods show promise, achieving in-situ microscale porosity has remained a critical hurdle. Unlike existing industry platforms, EMPATCH overcomes these limitations by offering an ultrathin, breathable, and water-permeable patch that comfortably conforms to the skin. Leveraging a phase-separated float assembly (PSFA) technique, we enable rapid, facile, large-area (>200 cm²) fabrication of ultrathin elastic patches (~1 µm) and phase-separated porous elastic sensors (~6 µm) by inducing in-situ phase separation of silver nanowires (AgNWs) and thermoplastic polyurethane (TPU) matrices at the water–air interface. This innovation culminates in an ultrathin, porous electronic skin that maximizes wearer comfort, ensures unobtrusive continuous monitoring, and provides a practical, scalable solution for real-time emotion tracking in therapeutic healthcare settings.

The EMPATCH platform demonstrates few-shot learning artificial affective intelligence through pretraining a majority of the model weights across four out-of-domain datasets, demonstrating the capabilities of observational models to accommodate small niche datasets within academia. We validate the model’s flexibility through few-shot learning on 60 samples from the WESAD dataset. Additionally, we showcased in-home closed-loop therapy using generative visual, audio, haptic, and holographic feedback, with each modality targeting distinct positive (PA) and negative (NA) affective states. This work not only reinforces Ekman’s theoretical framework by linking universal physiological and psychological domains but also sets a new benchmark for closed-loop, personalized therapeutic interventions—opening avenues for automated, in-home mental health therapies. Further integration of fragmented datasets from the literature will strengthen our understanding of physiologically based emotions, ultimately leading to the first domain-agnostic psychophysiological model. In this regard, observational models represent a robust, generalizable framework that links models with new experimental biomarkers and stressors with minimal training, enabling clinically actionable insights for human emotion and activity recognition (HEAR).

By bridging universal physiological and psychological domains, this work reaffirms Ekman’s theoretical framework while establishing a new standard for individualized, closed-loop therapeutic interventions. The prospective integration of fragmented datasets from the literature will advance our understanding of how physiological metrics map onto emotional states, propelling us toward the first domain-agnostic psychophysiological model. In this context, observational models offer a robust, generalizable framework that can swiftly align with new biomarkers and stressors. When applied to the EMPATCH platform, these models facilitate clinically actionable insights for human emotion and activity recognition (HEAR), ultimately elevating the impact and accessibility of in-home mental health therapies.

By employing meta-learning strategies with stable neural operators, we begin forming a suitable framework for human emotion and activity recognition (HEAR) that addresses the previous modeling bottlenecks by learning temporal patterns across new experimental modalities.

**Discussion.**

**Conclusion.**

This has allowed companies like Fitbit and Apple Watch to deviate from reporting clinically meaningful anxiety-metrics for niche pseudo-anxiety scores16.

The main research challenge therefore lies not in the conceptual link between physiology and anxiety, which is a superposition of basic emotional states, but in translating this relationship into a universal, data-driven model.

The smallest subset of emotions are labeled basic emotions, which are visually identifiable through universal facial expressions:9 observations that are not socially learned10. Such universal emotional reflexes are likely derived from an evolutionary adaptation that primes the body to confront potential threats, such as squinting in disgust to block harmful stimuli10.

Despite these innovations, training deep learning models can be unstable due to exploding and vanishing gradients that must be mitigated by controlling the expressibility (Lipschitz constant) of any layer20. Currently, these effects can be indirectly dampened through spectral normalization and gradient clipping, which distorts the optimal gradient-based layer-specific updates20.

to accommodate irregular sampling intervals by interpreting discrete observations within a continuous functional domain, smoothing latent representations to handle missing or unseen nearby points without introducing non-trivial artifacts during signal alignment.

We maintain a lossless embedding through reversible layers. Modern reversible architectures in the literature, such as normalizing flows, maintain invertibility through pseudo-residual connections and affine coupling layers that maintain invertibility by spatially splitting a feature vector to process the information independently as discontinuous temporal segments. In contrast, observational models take advantage of temporal information through unitary transformations by learning the upper right triangle coefficients of a skew symmetric tensor (A). Matrix exponential [exp(A)] of any skewed symmetric operator yields a transformation within the Lie special orthogonal group SO(n), which is comprised of norm-preserving rotational matrices. By applying the linear layer within a reversible non-linearly subdomain, we allow the data to further scale in magnitude, which is critical to maintain the layer as a reversible universal function approximator.

By constraining the non-linear magnitude, we additionally constrain the Lipschitz constant to be normally distributed with µ of 1.001 and σ of 0.0027, which stabilizes the gradient flow within deep networks. By preserving the initial signal variance, we further limit unstable degenerate output solutions that rely on large covariant shifts.

within a more focused study, the STAI-Y2 form has an even narrower internal consistency of 0.87–0.91 for student populations15

**Discussion.**

**Conclusion.**

We validate our model by metatraining four unique psychophysiological datasets concurrently, with few-shot training on two unseen models that uses common industry-grade as well as novel laboratory-fabricated platforms to ensure that OL models can generalize across both industry and academic pipelines.

Observational models therefore represent a method for linking different latent spaces through learning a single embedded space that connects different datasets.

**SUPPLEMENTARY:**

Unfortunately, within physiological datasets, there inherently exist motion artifacts and noise that can bias data interpretations, which is only exacerbated by the relatively small size of physio-emotion datasets compared to traditional large language models. To learn how to deal with these events, we employ meta-learning techniques to share weights and integrate multiple datasets together. Each path to the physiological profile can be broken up into 3 main sections: a signal-specific layer, shared meta-learning layer, and another signal-specific layer. Most of the model weights lie within the meta layer, removing the burden of small datasets, while the signal specific layers provide dataset-specific expressibility. Each signal-specific layer address subproblems within the broader task of physiological-emotion mapping, enabling few-shot learning on previously unseen datasets. Our core model has demonstrated strong performance after training on four physiological meta-datasets from the literature (EMOGNITION, DAPPER, AMIGOS, and CASE) and has shown few-shot learning capabilities on two out-of-domain datasets that we compiled (EMPATCH, WESAD).

As illustrated in Fig. 2a, the fabrication begins with the preparation of a precursor solution containing polymer solution (TPU in tetrahydrofuran (THF)) and conductive filler solution (AgNWs in ethanol). Upon the injection of the nanocomposite solution into water bath, phase separation initiates due to the evaporation and dissolution of the volatile solvent (THF) and non-solvent (ethanol) into water bath, whereas water-immiscible TPU stays on water surface. This results in macroscopic Marangoni flow and microscale liquid-liquid demixing simultaneously (Fig. 2b). On the one hand, dissolution of THF and ethanol lowers the local surface tension, which results in a circular surface tension gradient near the droplet (Fig. 2b, (i)). This gradient induces Marangoni flow from the center to the boundary, which pushes the boundary expansion and mass flow of the precursor solution. This leads to a partially dried ultrathin nanocomposite film floating at the water-air interface. On the other hand, concurrent liquid-liquid demixing results in phase separation of the TPU-rich and TPU-poor phases (Fig. 2b, (ii)). Ag NWs with amphiphilic ligands (that is, polyvinyl pyrrolidone) reside in the PU-poor phase due to its immiscibility with TPU solution. This process generates co-continuous phases in three dimensions, completed by drying that creates continuous porous structures within the PU matrices.

The resulting porous nanocomposite consists of randomly distributed AgNWs confined within porous polymer matrices (Fig. 2c), forming conductive percolation networks that bridge interconnected pores across multiple scales. Unlike conventional spin-coating processes, the PSFA method enables the fabrication of large, thin, yet adhesive electronic skins suitable for multimodal stress therapy. These devices are stretchable, ultrasoft, and provide conformal contact with the skin for enhanced comfort and unobtrusiveness (Fig. 2d–f). Additionally, the porous conductor demonstrates exceptional durability and reliability, with only a slight resistance change (R/R₀ = 4.8) after 3,000 cycles of 25% stretching, compared to the non-porous control (R/R₀ > 200; Fig. 2h). The multiscale interconnected cellular structure further enhances porosity and breathability, facilitating skin perspiration (Fig. 2i) and improving long-term biocompatibility (Fig. 2j, k).

To evaluate the performance of our porous conductor for electrophysiological signal recording, we first examined the electrode-skin contact impedance. The ultrathin porous electrode showed notably reduced impedance compared to its thicker counterpart, primarily due to its intimate skin contact (Fig. 2l). Furthermore, electrooculogram (EOG) signals recorded before and after sweating using the porous on-skin sensors demonstrated quantitatively comparable patterns to those obtained with Ag/AgCl gel electrodes (Fig. 2m, n). Lastly, we present a comprehensive comparison of our Empatch with state-of-the-art materials fabricated by other methods, such as spin-coating and float assembly4, in terms of processing efficiency, large-area fabrication, breathability, wearability, sweat resistance, and electrical conductivity (Fig. 2o).

To accommodate dynamic skin deformations, we utilize strain-resilient interconnects composed of a porous liquid metal composite6, which enables reliable and robust sensing and therapeutic capabilities. This performance is demonstrated by the proper operation of a light-emitting diode array (Fig. 2p), which can be attributed to the stable electrical resistance of the interconnect under strain (Fig. 2q) and its resilience to various damage scenarios, including scalpel punctures, hammer impacts, and tweezer pricks (Fig. 2r). Furthermore, electrocardiogram signals recorded using the liquid metal composite wiring showed negligible variation before and after stretching (Fig. 2s).

probing how the hidden state (p-profile) collectively justifies each observed signal (input feature).

predict each observable signal, By training the model from output (p-profile) to input (signal recordings), missing signal data, whether partial or full, do not invalidate other observations, since the model can justify each timepoint individually.

By training the model from output (the p-profile) to input (the measured signals), OL accommodates varying sampling frequencies and missing data, since the absence of one biomarker does not invalidate another. Each input is treated as an observable event explained by the hidden state, allowing the model to justify every discrete biological reaction individually. This decoupling of biomarkers from the core physiological representation reduces the need to discard samples due to motion artifacts or lost data packets. In doing so, OL fosters flexible, out-of-domain integration of time-series datasets,

Unfortunately, within, most datasets (e.g., WESAD, AMIGOS, CASE, Emognition, and DAPPER) have little to no overlap within biomarkers and emotion labels, complicating efforts to validate models against a universal standard (**SXX**).

Importantly, incorporating invertible and bijective formulations ensures that the transformations remain one-to-one and information-preserving, thereby enhancing reproducibility and interpretability. Together, these innovations establish a rigorous, flexible architecture poised to unify fragmented physiological datasets and deliver universally applicable, clinically meaningful insights into the emotional states that underpin human health and behavior.

To address the fragmented and sparse nature of current physiological emotion datasets, emerging scientific machine learning techniques such as meta-learning and neural operators offer powerful solutions. Meta-learning enables models to share a common set of core parameters, allowing rapid adaptation to new biomarkers and labeling schemes with minimal data, while neural operators map discrete, infinite-dimensional inputs to continuous functional spaces for smooth interpolation across out-of-domain conditions. By integrating invertible and bijective components, these neural operators ensure one-to-one, lossless correspondences that enhance reproducibility and reliability.

Further research into neural operators has

a core set of shared weights

By mapping discretely sampled, infinite-dimensional input-output spaces through continuous functional forms, neural operators (NOs) address these challenges by easily interpolating across unseen, out-of-domain examples. Integrating invertible networks within NOs further ensures a one-to-one lossless correspondence between input and output domains, providing a robust validation mechanism across different datasets and experimental conditions. Bijective neural operators (BNOs) further address the reproducibility issue within scientific modeling by limiting the number of solutions the model can converge to, ensuring consistent and reliable outcomes. By offering a rigorous and scientifically grounded approach, BNOs hold promise for solving many of the reproducibility problems in current scientific modeling for physiological datasets.

This is achieved through a series of reversible, learnable transformations that connect input and output states. By mapping all the biometric responses to the p-profile, OL models effectively learn a unified representation of a patient’s physiological state while maintaining the ability to add new biomarkers and timepoints as needed. Each observable event could therefore be considered a weak classifier of the p-profile, where more observations increase the prediction confidence.

When data is missing, which is a problem in any real-time wearable platform, the weak classifier cannot be used to reconstruct the physiological profile. Fortunately, once the model weights are trained and frozen, few-shot learning can be employed during inference to approximate the p-profile and provide a causal explanation (e.g., Granger causality) for each observation.

Machine learning techbiques for multimodal things

This lack of biomarker and emotion validation promotes dataset-specific architectures that prevents data compilation and collaboration for an open-source generalizable physio-emotion model.

By reformulating the problem-space, observational models are reversibly mapping the input-output spaces through unitary layers in non-linear subdomains,

We present observational learning (OL) as a new foundational architecture for overcoming the current challenges with merging out-of-domain time-series datasets by decoupling biomarker and emotion weights, providing the model with a trainable path for different input signals and output emotions as seen within separate physio-emotion datasets currently in the literature. In OL models, each physiological feature (observable event) is treated as a response from a hidden biological perturbation, which we refer to as the physiological profile (p-profile). Observational learning therefore mimics the scientific method when solving an inverse problem (hidden state dynamics) by probing a system (p-profile, output state) and observing how the resulting perturbations (time series signals, input features) respond. Missing full or partial features do not invalidate other observations, allowing the model to backpropagate on incomplete datasets, minimizing the number of discarded samples. OL models can therefore learn the p-profile based on how well the hidden state can justify each observed vital sign collectively, using a core set of reversible learnable transformations between the output and input states. This allows us to condense all relevant physiological information within a common structure while maintaining the flexibility to add or remove new biomarkers and timepoints in the future. Once the p-profile has established a path to all observations, the network can be inverted to reconstruct the p-profile from any of these weak classifiers. Unfortunately, if samples are missing, as is common in real-time recordings, the model cannot affectively project the samples into the wavelet domain. Therefore, after the weights of the model are fixed, during inference, few-shot learning of the physiological profile can still explain (granger-cause) each observation.

The forward method cant be done.

By training the inverse model using a reversible map from the output latent manifold to a given input biomarker, OL architectures easily adapt to a new set of biomarkers as well as missing biomarker data, allowing researchers to meta-train on different real-world physiological datasets with a common set of shared weights.

Spielberger used this as a foundation for quantifying s-anxiety through the State-Trait Anxiety Inventory (STAI) questionnaire, which has undergone multiple independent assessments for validity and reliability across different cultures11–13, age groups, occupations, race, gender, and languages. Paul Ekman mapped these emotions to facial expressions within the Facial Action Coding System (FACS), proving that certain physiological responses are universally associated with emotions across cultures. Further analysis by

In 1895, Sigmund Freud realized that anxiety can be fully explained by discrete emotions, which according to the 1894 James-Lange theory meant that anxiety can be fully explained by physiology.

researchers have been unable to isolate single physiological signals that yield deterministic emotional states within a subject, partly due to the subjective interpretation of emotions and the complexity of physiological responses within the broader context of relatively small and noisy datasets.

WESAD dataset includes 15 subjects with wrist and chest recordings labeled with state anxiety scores, while the AMIGOS dataset involves 40 subjects with brain recordings labeled using the Big Five Inventory questionnaire. As relatively small and specific datasets, neither model has been used to generalize across other stress inducing activities nor validated against each other.

In contrast, mental health lacks comparable rigor, partly due to the subjective nature of emotions.

While physiological theories like Schachter-Singer’s two-factor model and Ekman’s Facial Action Coding System suggest measurable links between physical responses—such as heart rate or facial expressions—and emotions, attempts to identify deterministic biomarkers have failed due to the fragmented, noisy, and sparsely sampled nature of datasets.

In parallel, Schachter and Singer found that emotions are causal to physiological reactions, with the mind interpreting the body’s reaction as a ‘feeling,’ fundamentally link anxiety and physiological responses.

The continuous monitoring of mental health through wearable devices poses a unique and pressing challenge as compared to tracking physical well-being. While there is extensive literature documenting biomarker implications for physical illnesses, such as the Framingham Risk Score17, Susceptible-Infectious-Recovered model21, and the progression of diseases like Covid-19, mental health lacks clear, unbiased, and reproducible models. This knowledge gap becomes critical when addressing long-term anxiety, as acting on poorly understood models may exacerbate mental deterioration and lead to more severe conditions such as depression.

Without any standardized approach, physiological-based emotion modeling has been widely accepted within the psychological community

Anxiety modeling has been a longstanding endeavor in psychology. In 1895, Sigmund Freud defined anxiety as arising from emotional states, linking sensations such as tension, nervousness, and apprehension5. In 1966, Cattell distinguished anxiety that arise from emotional states and personality traits6. Building upon these definitions, Spielberger introduced the State-Trait Anxiety Inventory (STAI) in 1983 (Fig. 1), a well-investigated questionnaire that has undergone multiple independent assessments for validity and reliability across different cultures7–9, age groups9, occupations, races8, gender9, and languages. The STAI exam numerically quantifies both short-term, emotionally based state anxiety (S-anxiety) and long-term, personality-based trait anxiety (T-anxiety)10. Despite its population-based correlation to S-anxiety, the STAI survey relies on subjective user ratings of emotions, introducing biases to individual scores.

We validated the generalizability of the to new datasets via commercial and novel electronic skin wearable devices.

to decode well-observed physiological patterns within humans

The p-profile represents a signal-agnostic manifold: a latent construct capable of explaining each biological reaction independently.

Here, we present the first bidirectional wavelet neural operator (BWNO) trained within a newly proposed observational learning (OL) framework designed to overcome the current limitations of wearable datasets to develop the first open-sourced physio-emotion model as well as real-time personalized anxiety therapy.

, suggesting that some affective and physiological states are intrinsically linked. Spiel,

The problem of developing a reliable universal affective computing pipeline is hindered by sparse, biomarker-specific, and unevenly sampled wearable datasets, limiting the applicability of machine learning models that require large datasets and rely on domain-specific attributes.

By training the inverse problem, observational learning solves a key issue within wearable data analysis as the architecture does not require evenly sampled nor specific input features. This is achieved by projecting the PP manifold into the Fourier domain, solving the inverse problem, and mapping the oversampled solution back into the spatial domain at unevenly sampled time points. The key to convergence for OL models relies on the set of information being strongly correlated across different signal combinations, so that one can isolate a common domain with minimal signal-specific weights. For physiological data, prior literature has demonstrated this correlation through state-space models and multivariate regression, where heart rate data can be hallucinated through respiratory information. We use a 1:16 ratio for dataset-specific to shared weights, allowing for small datasets to be easily interfaced within our framework with minimal training. Within this framework, each biomarker serves as evidence – a weak classifier – for the underlying perturbation rather than as a mandatory input, where the model is trained from the hidden variable to the observed signals. We have demonstrated this through partially and fully masking out a given signal, while converging to a similar PP manifold to reconstruct the missing points.

The problems in compiling enough trainable data to associate physical and mental states prevent simple classification systems such as decision trees and fully connected networks from converging and generalizing across datasets. The main obstruction for using more complex predictors, is the lack of standardization across the literature for which physiological stimuli (sweat-metabolites, facial expressions, vital signs) as well as emotional responses (positive and negative affective states) should be recorded for a complete and universal physio-emotional dataset. Currently, there is no universal physiological model for emotion classification as many datasets compiled in the literature – WESAD, EMOGNITION, DAPPER, AMIGOS, and CASE – are signal-specific.

Compiling large datasets is hard and time consuming.

, each emotion model is only trained on a selective and highly specialized dataset, where it is impossible to generalize across publications. This problem is exacerbated by black-box machine learning techniques, which hinders how relevant any emotion study is to one another. Further issues include resampling features to match a neural architecture, random information loss during data transmission, sampling bias from emotion questionnaires, as well as data sparsity compared to the number of learnable parameters. Modern advancements in machine learning techniques including text-based sentiment analysis as well as neural operators offer a new way for overcoming these issues within the broader context of universal affective computing.

In this work, we present the first bidirectional wavelet neural operator (BWNO) trained through observational learning (OL).

Unlike fixed models, each new observation acts as a weak classifier, increasing the confidence that the manifold represents the body’s current state. We claim that missing or unaligned data points, which typically degrade model performance, have a limited impact on this flexible architecture.

One key innovation that allows observational learning the flexibility to generalize across input domains is bidirectional training. Through diffeomorphic transformations, OL models independently map the common ancestor to each observable output using a set of invertible weights, allowing for both inference and interpretation depending on the direction. During training, the model learns how to remove information from the manifold to validate each observation. While projecting different spaces into a common latent space is extremely difficult, by inverting the weights in observational learning during inference, the model can transform each individual signal into the manifold’s space. Each projection inherently contains noise that is smoothed out when considering all observations together. This approach mirrors scientific experiments, where multiple correlated observations are used to reconstruct the underlying properties of a system. Consequently, this architecture provides an interpretable framework for machine learning researchers, emphasizing not only the final predictions but also the mappings across each space, offering deeper insights into physiological events and their associated emotional responses.

**Discussion.**

Here we present our analysis from capturing real-time physiological signals in response to four unique experimental stressors, including music, cold pressure, exercise (biking), and virtual reality, to investigate the relationship between physiology and emotional responses. The custom-designed patch integrated four key sensors—electrooculography (EOG), electroencephalography (EEG), electrodermal activity (EDA), and temperature—enabling the continuous recording of both electrical and thermal signals (Fig 3a). These sensors provided rich, multidimensional data that form the foundation of the analysis.

**Device Design and Signal Processing**

Our device is composed of EOG, EEG, EDA, and temperature sensors that conformally adhere to the surface of the skin. Signals are collected and processed through a series of filters, amplifiers, voltage regulators, and a microcontroller unit (Fig 3bc). This robust design ensured that signals were processed in real-time and transmitted for further analysis.

Signal preprocessing, illustrated on the top right, involved filtering the raw physiological data to remove noise and artifacts while preserving essential features related to emotional states. The filtering and amplification stages were particularly important in handling high-frequency noise in EEG and EOG recordings, while EDA and temperature data required low-pass filtering to stabilize readings. These preprocessing steps ensured the data was clean and interpretable for the subsequent analyses of emotional responses.

**Real-Time Data Collection from Stressors**

The figure presents representative datasets from four different stressors—cold pressure, exercise, music, and virtual reality—demonstrating the robustness of the device in capturing physiological signals across various conditions. The datasets are displayed in the middle portion of the figure, showing the raw signal patterns for each stressor.

In the cold pressure and exercise experiments, we observed clear variations in physiological responses. For example, alpha power from the EEG readings, which are known to decrease during times of anxiety, distinctly dropped during the cold pressure test, indicating increased sympathetic nervous system activity. Similarly, temperature fluctuations were evident during the cold pressure experiment, correlating with participant discomfort. In contrast, music and virtual reality experiments yielded more moderate physiological changes, suggesting these stressors were less intense.

**Positive and Negative Affectivity Scores**

We also analyzed affective responses through positive and negative affectivity scores, focusing on how these scores varied across the cold pressure and exercise experiments. As shown in figure 3e, affectivity scores derived from physiological data showed distinct patterns. Cold pressure led to an overall increase in both positive and negative affectivity, while exercise was able to boost positive affectivity and decrease negative affectivity. The graphs show overlapping yet distinguishable distributions of affective states, with cold pressure eliciting a strong negative response and exercise producing mixed emotional states.

**Emotional Distributions and Correlations**

The violin plots (3g) represent the distribution of emotional states as measured by the State-Trait Anxiety Inventory (STAI). These distributions capture the range of emotional intensities experienced by participants, highlighting the variability across different stressors. Cold pressure induced a broader distribution of negative emotions compared to exercise, which showed a wider spread across both positive and negative affective states.

Lastly, the correlation analysis from the Positive and Negative Affect Schedule (PANAS) revealed significant relationships between emotional states (3h). The correlations confirm the model’s ability meta-learn a core set of transformations, while leaving only a small set of weights to differentiate each emotion.

**Implications for Personalized Interventions**

The data gathered from this study not only validate our device’s capacity to measure physiological responses but also demonstrate its potential in developing automated, personalized mental health interventions. By accurately mapping physiological signals to emotional profiles in real time, our approach could be used to tailor interventions such as music or virtual reality therapy to a patient's emotional state, offering a novel method for treating anxiety and mood disorders.

The results also set a strong foundation for future work, where further validation across larger and more diverse datasets will be critical. The combination of wearable sensors and machine learning can provide increasingly precise mappings between physiology and emotional states, ultimately leading to more robust, domain-agnostic models for therapeutic applications.

The intrinsic softness, thickness, and gas permeability of skin-interfaced electronics hold promise for long-term and continuous high-fidelity monitoring of physiological states. Recently, there has been many exciting progresses in the fabrication of ultrathin and soft wearables, as evidenced by elastomeric nanofiber mats1 and elastic conductor with microcracked structures2 and semiconductors3. While these devices exhibited seamless contact with skin, the fabrication typically involves electrospinning, iterative spin coating, and thermal evaporation, which are laborious and time-consuming. Moreover, the manufacture of large patches to cover the head or face presents challenges due to limitations in dimensions imposed by instruments such as spin-coaters and oxygen plasma cleaners. While the float assembly method shows promise4,5, achieving in-situ generation of microscale porosity remains fundamentally challenging.

Here, we present a phase-separated float assembly (PSFA) technique that achieves in situ phase separation of silver nanowires (AgNWs) from thermoplastic polyurethane (TPU) matrices at water-air interface. This process enables rapid (in minutes), facile and large-area (>200 cm2) fabrication of ultrathin elastic patches (~1 µm) and phase-separated porous elastic sensors (~6 µm). The resulting ultrathin porous electronic skin exhibits substantial improvement in unobtrusiveness, comfort, and intimate contact with skin. As illustrated in Fig. 2a, the fabrication begins with the preparation of a precursor solution containing polymer solution (TPU in tetrahydrofuran (THF)) and conductive filler solution (AgNWs in ethanol). Upon the injection of the nanocomposite solution into water bath, phase separation initiates due to the evaporation and dissolution of the volatile solvent (THF) and non-solvent (ethanol) into water bath, whereas water-immiscible TPU stays on water surface. This results in macroscopic Marangoni flow and microscale liquid-liquid demixing simultaneously (Fig. 2b). On the one hand, dissolution of THF and ethanol lowers the local surface tension, which results in a circular surface tension gradient near the droplet (Fig. 2b, (i)). This gradient induces Marangoni flow from the center to the boundary, which pushes the boundary expansion and mass flow of the precursor solution. This leads to a partially dried ultrathin nanocomposite film floating at the water-air interface. On the other hand, concurrent liquid-liquid demixing results in phase separation of the TPU-rich and TPU-poor phases (Fig. 2b, (ii)). Ag NWs with amphiphilic ligands (that is, polyvinyl pyrrolidone) reside in the PU-poor phase due to its immiscibility with TPU solution. This process generates co-continuous phases in three dimensions, completed by drying that creates continuous porous structures within the PU matrices.

The resulting porous nanocomposite consists of randomly distributed AgNWs confined within porous polymer matrices (Fig. 2c), forming conductive percolation networks that bridge interconnected pores across multiple scales. Unlike conventional spin-coating processes, the PSFA method enables the fabrication of large, thin, yet adhesive electronic skins suitable for multimodal stress therapy. These devices are stretchable, ultrasoft, and provide conformal contact with the skin for enhanced comfort and unobtrusiveness (Fig. 2d–f). Additionally, the porous conductor demonstrates exceptional durability and reliability, with only a slight resistance change (R/R₀ = 4.8) after 3,000 cycles of 25% stretching, compared to the non-porous control (R/R₀ > 200; Fig. 2h). The multiscale interconnected cellular structure further enhances porosity and breathability, facilitating skin perspiration (Fig. 2i) and improving long-term biocompatibility (Fig. 2j, k).

To evaluate the performance of our porous conductor for electrophysiological signal recording, we first examined the electrode-skin contact impedance. The ultrathin porous electrode showed notably reduced impedance compared to its thicker counterpart, primarily due to its intimate skin contact (Fig. 2l). Furthermore, electrooculogram (EOG) signals recorded before and after sweating using the porous on-skin sensors demonstrated quantitatively comparable patterns to those obtained with Ag/AgCl gel electrodes (Fig. 2m, n). Lastly, we present a comprehensive comparison of our Empatch with state-of-the-art materials fabricated by other methods, such as spin-coating and float assembly4, in terms of processing efficiency, large-area fabrication, breathability, wearability, sweat resistance, and electrical conductivity (Fig. 2o).

To accommodate dynamic skin deformations, we utilize strain-resilient interconnects composed of a porous liquid metal composite6, which enables reliable and robust sensing and therapeutic capabilities. This performance is demonstrated by the proper operation of a light-emitting diode array (Fig. 2p), which can be attributed to the stable electrical resistance of the interconnect under strain (Fig. 2q) and its resilience to various damage scenarios, including scalpel punctures, hammer impacts, and tweezer pricks (Fig. 2r). Furthermore, electrocardiogram signals recorded using the liquid metal composite wiring showed negligible variation before and after stretching (Fig. 2s).

**Methods.**

While rapid processing and reaction to physiological cues are a core function of the human body, the intricacies of how this occurs are not fully understood.

Modern approaches using machine learning and wearable devices are now exploring how everyday biomarkers contribute to one’s inner psychological state.

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